

Introduction to

PopcornSAR Adaptive AUTOSAR (R20-11) Tool chain

March. 2022



Index

- 1. Automotive Software Development Process with Adaptive AUTOSAR (R20-11)
- 2. Overview of PopcornSAR Adaptive AUTOSAR (R20-11) tool chain
- 3. Product introduction: PARA
- 4. Product introduction: PACON IDE
- 5. Product introduction: Virtual ECU
- 6. Example of PopcornSAR AP development environment
- 7. PopcornSAR AP tool roadmap(~2023)

(Appendix 1) Tool demonstrations

(Appendix 2) ISO26262 Certificate of PopcornSAR Adaptive platform Authoring tool



1. Automotive Software Development Process with Adaptive AUTOSAR (R20-11)

- 1. PopcornSAR provides automotive software development tool chain for Adaptive AUTOSAR Applications(AA).
 - Supporting the whole development process of Adaptive Applications/ECUs for OEM/Tier1.
- 2. Able to automate the whole development process based on CI/CD after the initial manual development.
- 3. Yocto SDK is used for Adaptive application(AA) development after the SOP.





1. Automotive Software Development Process with Adaptive AUTOSAR (R20-11)



 After testing on virtual ECU, developers need to conduct system test on the physical ECU.



• Vehicle functions and cyber security can be updated through OTA after SOP.



2. Overview of PopcornSAR Adaptive AUTOSAR (R20-11) tool chain

- A development platform with tools installed in PC
 - (1) SDK of Adaptive Platform(AP) Functional Cluster(FC) or Vehicle APIs (No dependency on middleware vendor).
 - 2 Providing virtual ECU (simulation & test), supporting programing languages like C + +.
 - **③** Coding Rule check, API autocomplete, etc.





3. Product Introduction : PARA - FCs list (R20-11) To-be (before 2023)



3. Product introduction: PARA - Features

- 1. PARA enables Adaptive Application tests without Execution Management(EM).
 - According to AUTOSAR standard, EM is essential. However, PARA users can develop/test adaptive applications without EM, increasing development efficiency.
- 2. If no problem is found in ARXML Validation, no more parameter is needed for PopcornSAR's generators, and the generation will be done automatically.
 - AutoSAR.io includes generators of FC, so it automatically analyzes Adaptive Applications and Machine, and generates related source codes and Manifest files.
- 3. PopcornSAR can migrate results(C++) from Matlab/Simulink 2021a(R19 11) or AP M odel Based Design(MBD), Legacy MBD into Adaptive applications, and related guidelines are also available.
 - It's necessary to use Matlab/Simulink to develop Adaptive Applications for control.
- 4. PARA supports Python's SOME/IP for AI development.



3. Product introduction: PARA - Features

3 • 🗑 🐚 🚀 • [원 • 전 • 학 🗢 • 학 • [편			Q 181
🖲 AUTOSAR Explorer 🛙 📃 🥵 🕴 🐡 🗖 🛃 Adaptive	Application Designer 🛛 🛣 AUTOSAR System Design	r 🖪 Adaptive Machine Designer 🗧 AUTOSAR Design Validation 🗉	-
E 20210730	NAME	DESCRIPTION REPORTS	
in 20210831	Parente -	DESCRIPTION OF TRACE	
20210831_com-somip-basic			
AP_MBD			
🖻 ara-adi			
Bm_Aux			
Bm_Aux_20210830			
Bm_Aux_20210907		PARA Generator - C X	
Bm_Aux_EM			
Bm_Aux_Original			
Com-someip-event		ARA TYPE GENERATOR VALIDATE GENERATE	
com-someip-event-ECUcommunication		🖾 ara::exec man Machine 📀 DONE 💿 DONE	
gen-manifest		🖾 ara::exec man Execution 🔹 DONE 🔹 DONE	
> 🗁 gen-src		E ara::com code Implementation Data Types O DONE	
PARA_inter.arxml		Kara code Service Interfaces O DONE O DONE	
 Ø AUTOSAR 		Consistent code Service Interfaces Tool Service Down	
DataType		ara::com code Service interface impl Stubs V Duve V Duve	
DltLogChannelToProcess		🗠 ara::com man Service Instance 🔮 DONE	
Ethernet		🗹 ara::com man Raw Data Stream 🔮 DONE 🥥 DONE	
> Executable		🖾 ara::com man Communication Management 🔮 DONE 🧶 DONE	
FunctionGroupSet		ara::per man Persistency File Storage 💿 WAIT 💿 WAIT	
> 🖬 Machine		ara::per man Persistency Key Value Storage 💿 WAIT 💿 WAIT	
> Process			
ProcessToMachine			
SdConfig			
> E Service			
El StartupConfig			
StateMachine			
> 🖬 SwC			
Com-someip-event-uint32		GENERATE CLOSE	
i minimum_arxml			
📾 para-r2011-main			
ara-r2011-samples-main			
📓 per-example			
📓 radar		0	
a radar_fusion		1.5	
Radar_Kalman_regacy			
sm-drivingfg			
🔳 test			

<Generation finishes in average of 1 minute by PARA in AutoSAR.io>



3. Product introduction: PARA – Safety Mechanism for ISO26262

- PopcornSAR provides special safety mechanism(libpara) which is developed by
 PopcornSAR own. It can detect faults in execution level when AA is running, such as:
 - 1) Human errors in using ARA API when implementing Adaptive Applications,
 - 2) Human errors in using POSIX OS.

2021/11/19 08:08:04.216822 3612010536 101 ECU1 unde DFLT log verbose V 1 [[RCVR] REQ(OFFER) sess:1,sid:201,iid:2,maj:1,min:4294967295,p ath:/example/var/ara-channel/com/4600_BMS_AA_RootSwc_RequiredPort.service <= /example/var/ara-channel/com/4600_BMS_AA_RootSwc_RequiredP ort.tmp] 2021/11/19 08:08:04.216950 3612010537 102 ECU1 unde DFLT log error V 1 [CmRouter::ProcessOfferServiceReq:: not exist service fail <key:

pport:201:2:1:4294967295>] 2021/11/19 08:08:04.217106 3612010539 103 ECU1 unde DFLT log verbose V 1 [[SNDR] RES(OFFER) sess:1,res:not_supported => /example/var/ar a-channel/com/4600 BMS AA RootSwc RequiredPort.tmp]

<ex1 Human error of ara API : SOME/IP Error fault detection when AA runs: someip OfferService API>

2022/02/09 03:39:18.645278 102307244 001 ECU1 CM-- DFLT log error V 1 [InitByManifest:: ManifestParser::InitByManifest:: HasParserError fail <0> (/home/popcornsar/para-r2011-main/para-api/com/internal/database/database.cpp #63)] 5terminate called after throwing an instance of 'std::runtime_error' 6 what(): InitByManifest:: ManifestParser::InitByManifest:: HasParserError fail <0> (/home/popcornsar/para-r2011-main/para-api/com/internal/database/database.cpp #63)]

<ex2 Human error of POSIX OS : dummy files created when using vi editor of POSIX OS in target board>



3. Product introduction: PARA – CAN-DO(based on Docker container)

- CAN-DO can generate CAN virtual ECU which is based on docker container with ARXML/DBC/EXCEL.
- Able to fast generate multiple CAN virtual ECUs for testing ECUs.
- Able to manage CAN virtual ECU's configurations through Dockerhub, and able to automate the virtual ECU generation process through Jenkins.
- No limitation of AUTOSAR versions.





3. Product introduction: PARA – Example use case of CAN-DO



- Virtual CAN ECUs can be generated by CAN-DO <u>automatically</u>.
- Configurations can be saved & managed by Dockerhub/Docker registry.





Host OS AA (Adaptive AUTOSAR)

Docker Container (Non-AUTOSAR)

- EM might not recognize non-AUTOSAR Apps (docker, legacy network app, Python etc).
- PopcornSAR provides special AA as a role of EM/SM to execute Non-AUTOSAR Apps.



4. Product introduction: PACON IDE – Features

- 1. PACON IDE(=Docker Container) can be customized according to customer's needs.
 - Separate IDEs for different variants.
 - Customer's IDEs can be redistributed & managed through Jenkins CI/CD.
- 2. Has no dependency on Adaptive Platform Vendor.
- 3. Code developer can use Vscode to connect with PACON IDE.
 - Docker Container has essential extensions for using PARA & Vscode.
 - External network is not needed.
- 4. Wireshark is provided even if it's not installed in developer's PC.
- 5. Can be distributed through Jenkins CI/CD.
- 6. Provides additional features for efficient development.
 - Auto complete function for ARA API & open source API.
 - Real-time code rule check.
 - Debug.
 - Various programming languages (Python etc.,).



4. Product introduction: PACON IDE – Two variations of PACON IDE

① Develop within developer's PC

(Without external network)



② With connection to development server

(Increase convenience & efficiency based on remote co-working environment)



docker container : Distributed through Dockerhub





- Separate IDEs for different variants.
- Customer IDE can be redistributed & managed through Jenkins CI/CD.
- IDE must be redistributed according to updates of OS.

Jenkins Auto-distribution through Jenkins



4. Product introduction: PACON IDE - IDE and Virtual ECU creation process





1. PopcornSAR's virtual ECU can be customized according to customer's requirements.

- Separate virtual ECUs for different variants.
- Customer's virtual ECUs can be redistributed & managed through Jenkins CI/CD.
- 2. Virtual ECU has no dependency on Adaptive Platform Vendor.
- 3. PopcornSAR's Virtual ECU has lighter footprint, inducing efficient development with less compatibility issues than QEMU.
 - PopcornSAR provides virtual ECU(docker container) which corresponds to customer's physical ECU requirements(POSIX OS etc.).
 - After being tested on Docker Container, adaptive applications can be copied directly on target ECU.



- 4. Developers can generate virtual ECUs through PACON IDE.
- 5. Developers can develop multiple ECUs in docker container, manage their configurations through Dockerhub or Docker registry, and share their results with other colleagues.
- 6. Multiple virtual ECUs can be generated by Jenkins CI/CD for adaptive application tests.
- 7. PACON IDE provides additional docker containers for virtual ECUs to carry out other system tests.
 - Usually, it's difficult to add system testing software in virtual ECU. (Ex : Installing tshark in virtual ECU ARM)
 - PopcornSAR can generate additional docker containers for system testing software.



5. Product introduction: Virtual ECU – Customization according to requirements

• IDE and virtual ECU for the same variant are managed separately.



- Separate virtual ECUs for different variants.
- Customer's virtual ECU can be redistributed & managed through Jenkins CI/CD.
- Virtual ECU is compatible with PopcornSAR's/other ECUs.





5. Product introduction: Virtual ECU – Identical environment to target ECU



In case of QNX, virtual ECU will run on QEMU instead of docker container.

- Once testing is done in a development server, an adaptive application can be ported to target ECU without recompiling.
 - -> Maximizes efficiency in development.



5. Product introduction: Virtual ECU - QEMU vs Docker Container

	QEMU (AS-IS)	DockerContainer(To-be)
Real-time simulation for adaptive application in target board	X (Consuming ROM/RAM)	Ο
Virtual ECU configuration management	Х	0
Sharing with others	Х	0
Distribution through network	Х	0
Adding adaptive application in virtual ECU	Х	Ο
Others	_	Can connect to other docker containers for system tests



5. Product introduction: Virtual ECU - Examples

• Developer can test network by generating multiple virtual ECUs.



<Virtual ECU in PACON IDE>

<Terminal in PACON IDE>



5. Product introduction: Virtual ECU - Examples

- Can use tshark in Docker Container for system test to monitor virtual ECU(ARM, etc.).
- Can use Wireshark which is installed in PACON IDE.

× <u>F</u> i	le <u>E</u> dit <u>S</u> election <u>V</u> iew <u>G</u> o <u>R</u> un <u>T</u> erminal <u>H</u> elj	p	remote_test04.pcap	(read-only) - work [Container popcornsar/pop	cornsar_r20-11_wrl_lts21:1.1.1 (sycha	ae_101-para-network	:) @ ssh://popcorn:	ar@192.168.0	.15] - Visual Studio Code	– – ×
ß		≡ remote_test04.p	cap (read-only) ×							
	> OPEN EDITORS	network_test > 🗉	remote_test04.pcap							
0	〜 WORK [CONTAINER POPCORNSAR/PO 🖺 🛱 ひ 🗐	remote_test0	4.pcap (110 fra	mes, 64.778374 seconds, 12643 by	tes)	E RRB				
~	> vscode		<i>cu</i>							4
20	> 0730	Apply a display	tilter							ALAAE
62	> APD	Endpoints	Response Time	Statistics Export Objects Mi	.sc	1911年	<u> </u>			
~	> capture					0	5 10	15 20	0 25 30 35 40 45	50 55 60
_ <mark>æ</mark> >) git temp					Display			Bytes Frames	Advanced Graph
	v network test	No.	Time	Source	Destinati	ion	Protocol	Length	Info	
		1	0.000000	172.20.0.5	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
0		2	1.632546	172.20.0.4	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
-0	= enabled_protos	3	1.741338	172.20.0.6	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
Ш	⊨ heuristic_protos	4	3.000410	172.20.0.5	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
		5	4.467195	172.20.0.7	172.20.0.5		TCP	76	35002 → 35001 [SYN] Seq=0 Win=6	4240 Len=0 MSS=140
	Fremote_test04.pcap	0	4.467279	172.20.0.5	172.20.0.7		TCP	/6	35001 → 35002 [SYN, ALK] Seq=0	ACK=1 W1n=65160 L
	> origin	8	4.407507	172.20.0.7	224 0 0 1		SOME / TP_SD	112	SOME/IP Service Discovery Proto	win-04250 Len-0
(\mathbf{N})	> para_0730_lib_wrl_lts21/usr/lib64	9	4.744653	172.20.0.6	224.0.0.1		SOME/TP-SD	112	SOME/IP Service Discovery Prote	col [Offer]
•	> para_aa	10	4.964573	172.20.0.7	172.20.0.5		SOME/IP	61	SOME/IP Protocol (Service ID: 0	x0001, Method ID:
Logs	> python	11	4.965776	172.20.0.5	172.20.0.7		SOME/IP	61	SOME/IP Protocol (Service ID: 0	x0001, Method ID:
E9507	> python someip	12	6.003710	172.20.0.5	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
	> Radar Kalman	13	7.239530	172.20.0.7	224.0.0.1		SOME/IP-SD	84	SOME/IP Service Discovery Proto	col [Find]
	> temp	14	7.633527	172.20.0.4	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
	> test	15	7.745239	172.20.0.6	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
	> test	16	7.96/159	172.20.0.7	224.0.0.1		SOME/IP-SD	112	SUME/IP Service Discovery Proto	col [Subscribe]
	z test_container	18	8 557669	172.20.0.5	172 20 0 7		SOME/IP-SD	04 61	SOME/IP Service Discovery Proto	ty0001 Method ID:
	> trace	19	9.004144	172.20.0.5	224.0.0.1		SOME/IP-SD	112	SOME/IP Service Discovery Proto	col [Offer]
	> vECU1								,,,,,,	
	> vECU2	TERMINAL PORT	S PROBLEMS C	DUTPUT DEBUG CONSOLE					(j) t	ash + ∨ Ш 🔟 ^ ×
		popcornsar@29	9a9a573dc3:~/.w	<pre>ireshark\$ docker ps</pre>						
		CONTAINER ID	IMAGE		COMMAND	CREATED	STATUS	PORTS	NAMES	
		c6b063d8c781	popcornsar/po	pcornsar_r20-11_wrl_lts21:1.1.1	"/bin/bash /home/pop" "/bin/bash /home/pop"	26 hours ago	Up 26 hour	s	sychae_102-para-network	
		51719badf597	popcornsar/po	st container	"/hin/hash /home/non "	2 days ago	In 2 days	5	tshark skeleton-ecu	
		8f08ebdc7cab	popcornsar_r2	0-11_wrl_lts21	"/bin/bash /home/pop"	2 days ago	Up 2 days		test	
		5c092e211ded	popcornsarsal	es/nxp-s32g-wrl-lts21-std:1.0.0	"/sbin/init"	2 weeks ago	Up 2 weeks		proxy-ecu	
		50fc46ea3131	popcornsarsal	es/nxp-s32g-wrl-lts21-std:1.0.0	"/sbin/init"	3 weeks ago	Up 2 days		skeleton-ecu	
		popcornsar@29	9a9a573dc3:~/.w	ireshark\$ []						
8										
	\ OUTUNE							0	ine indiana mailalata	
503								€t	ime indices available	
0										



6. Example of PopcornSAR AP development environment

- PopcornSAR AP tool chain doesn't include QEMU nor Yocto.
- Since ARA API changes frequently for each AP version, PopcornSAR developed its own testing SW.



PopcornSAR

7. PopcornSAR Adaptive tool development roadmap (~2023)



- 1. R20-11 Autosar.io ARXML modeling :
 - Link : https://youtu.be/3FYzR0bQ44s
- 2. R20-11 generation & build for communication between
 - 2 Adaptive Applications :
 - Link : <u>https://youtu.be/HYqNEMrYYAw</u>
- 3. R20-11 ARA::DIAG demo:
 - Link : https://youtu.be/jvySoUdoAJs
 - Link : https://youtu.be/tm_Cr80d52w





ARCS

Certificate of Achievement

This is to certify that

PopcornSAR Co., Ltd. Development of an AUTOSAR Adaptive Platform Authoring Tool supporting Automotive OTA design and being qualified with Automotive Functional Safety

has successfully achieved

Functional safety process capability Level 1 for ASIL B base practices Nov. 22, 2021

 Standard

 ISO/IEC 33002:2015 Information technology – Process assessment – Requirements for performing process assessment Assessment Model

 SS 7740:2018 Road vehicle – Functional safety process assessment model

 SS 7740 supports to audit the processes of ISO 26262:2011 Road vehicles- Functional safety(all parts)

Gil Jo Kim Principal Assessor 82216102

Details of Achievement

Process ID	Durana Nama	Capability Level 1	
	Process Name	ASIL B base practices	
ENG.4.SE	Software requirements analysis	•	
ENG.5.SE	Software design	•	
ENG.6.SE	Software construction	•	
ENG.7.SE	Software integration test	•	
ENG.8.SE	Software testing	•	

